

Verification of population protocols with unordered data

Steffen van Bergerem

Roland Guttenberg

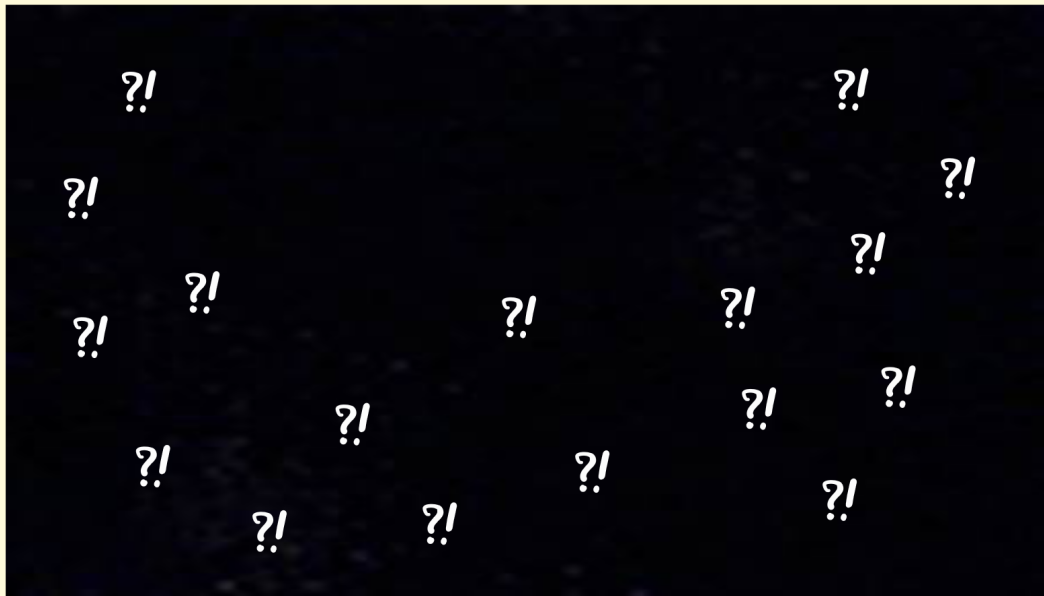
Sandra Kiefer

Corto Mascle

Nicolas Waldburger

Chana Weil-Kennedy





How to pass a law in the dark

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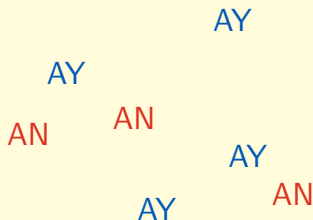
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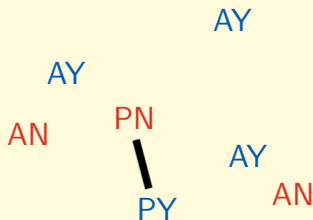
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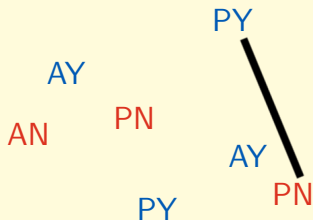
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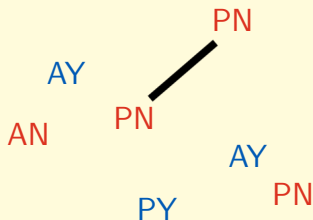
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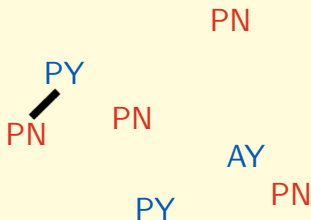
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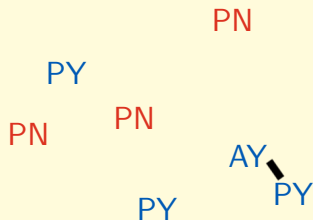
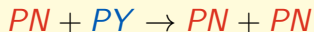
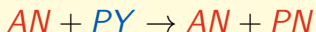
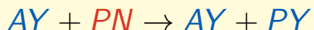
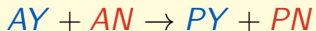
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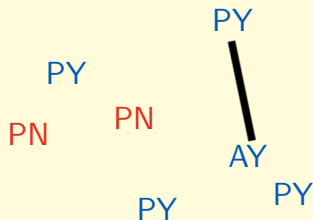
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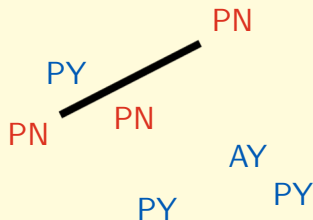
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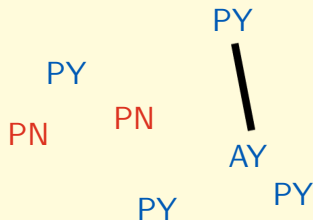
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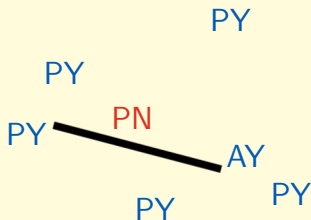
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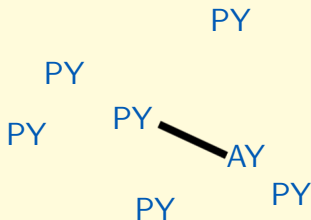
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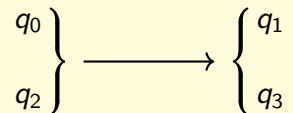


Population Protocols [Angluin, Aspnes, Diamadi, Fischer, Peralta, PODS 2004]

Finite set of states Q , with set $I \subseteq Q$ of *initial states*.

States are partitioned in two opinions $Q = Q_{\text{Yes}} \sqcup Q_{\text{No}}$

Interactions $\Delta \subseteq Q^2 \times Q^2$.

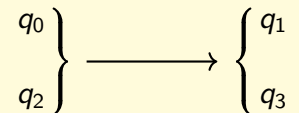


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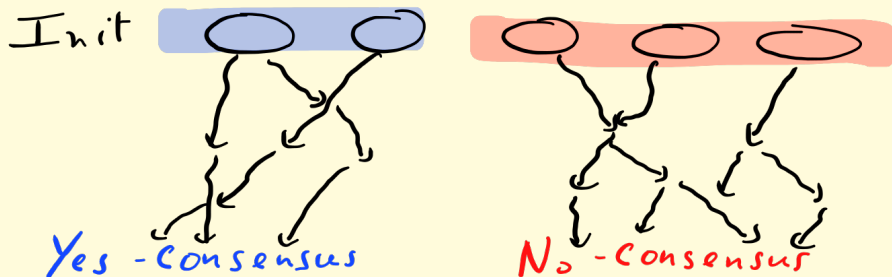
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The **predicate** computed by the protocol is then the set of initial configurations from which we reach a Yes-consensus.

First questions

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Can we check if a population protocol is well-specified? ✓

Theorem [Esparza, Ganty, Leroux, Majumdar 2017]

Checking if a population protocol is well-specified is **decidable** but as hard as Petri net reachability (Ackermann-complete).

Population Protocols with Unordered Data

Each agent carries a datum taken from an infinite set \mathbb{D} .

Interactions: $\Delta \subseteq Q^2 \times \{=, \neq\} \rightarrow Q^2$

Interactions take into account whether the two agents have $=$ or \neq data.

$$\left. \begin{array}{l} q_0, x \\ q_2, y \end{array} \right\} \xrightarrow{x \neq y} \left\{ \begin{array}{l} q_1, x \\ q_3, y \end{array} \right.$$

Majority predicate

Does some datum have more agents than all other combined?

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Open problem

What are the predicates computed by PPUD?

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Given a PPUD, is it well-specified?

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Theorem

It is **undecidable** to check whether a PPUD is well-specified.

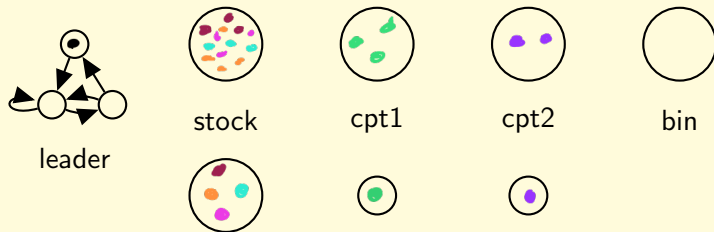
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leader



stock



cpt1



cpt2



bin

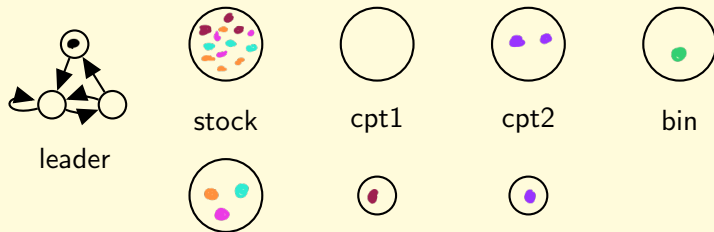
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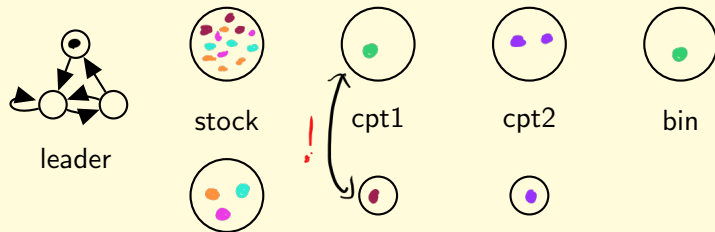
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Immediate Observation

A population protocol has the **Immediate Observation** property if in every interaction one of the two agents keeps the same state.

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Theorem (Esparza, Ganty, Majumdar, Weil-Kennedy 2018)

Well-specification is PSPACE-complete for Immediate-Observation population protocols without data.

Interval predicate = Boolean combination of

"At least 3 distinct data with between 1 and 3 agents in state q and 4 agents in state q' ".

$$\exists d_1, d_2, d_3, \bigwedge_{i=1}^3 (1 \leq \#(q, d_i) \leq 3) \wedge (4 \leq \#(q, d_i))$$

Theorem [Blondin, Ladouceur 2023]

The predicates computed by IOPPUD are exactly interval predicates.

IOPPUD

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Key lemma

Given a set of configurations C described by an interval predicate, we can compute interval predicates expressing $Pre^*(C)$ and $Post^*(C)$.

IOPPUD

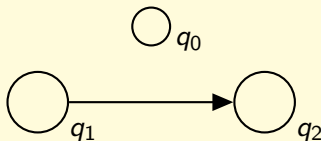
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In an IOPPUD, if an agent goes from q_1 to q_2 then we can send as many agents as we want from q_1 to q_2 .



IOPPUD

Generalised Reachability Expressions:

$$E ::= IP \mid E \cup E \mid E^c \mid Pre^*(E) \mid Post^*(E)$$

Theorem

Given a GRE E , we can compute an interval predicate for $\llbracket E \rrbracket_{\mathcal{P}}$.

Corollary

Given a GRE E , we can check if $\llbracket E \rrbracket_{\mathcal{P}} = \emptyset$.

Decidable problems on IOPPUDs

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- ▶ **Well-specification**
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- ▶ **Correctness**
= The protocol computes predicate P
- ▶ **Visible termination**
= If at some point all agents think True (False) then they will converge to True (False)
- ▶ **Home-space problem**
= Every fair run eventually reaches set of configurations H

Complexity

Emptiness of Generalised Reachability Expressions is:

In EXPSPACE

→ By controlling the growth of coefficients when translating GRE to Interval Predicates.

NEXPTIME-hard

→ By encoding the tiling of an exponential grid.

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